

Chapter 1: System of linear equation & Matrices.

1.1 Introduction

1.2 Gaus Elimination

1.3 Matrices

1.1 Introduction

In 2-D a line can be represented $ax+by=c \quad a,b \neq 0$

In 3-D a plane " " " $ax+by+cz=d \quad a,b,c \neq 0$

There are 3 ways to solve the system linear eq:

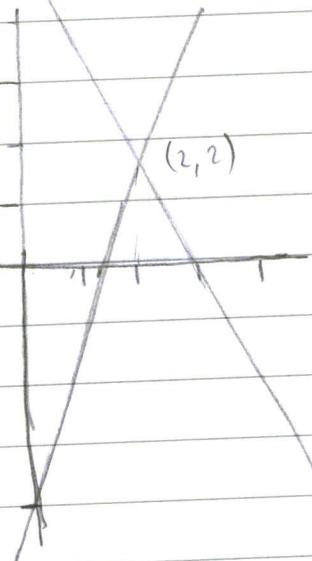
- (i) Graphically
- (ii) Algebraically using add & sub.
- (iii) Using Substitution.

~~we~~
(i) Graphically: Let's have two lines:

$$y = 3x - 4 \quad \text{and} \quad y = 2x + 6$$

$$\begin{array}{c|c} x & 0 \\ \hline y & -4 \end{array}$$

$$\begin{array}{c|c} x & 0 \\ \hline y & 6 \end{array}$$



(b) Solve ① & ② Algebraically

we can write eqn ① & ② as

$$3x - y = 4$$

$$2x + y = 6$$

$$5x = 10$$

$$\boxed{x = 2}$$

$$y = 3x - 4$$

$$= 6 - 4 = 2$$

$$\boxed{y = 2}$$

Systems of Equations

If there are two straight lines L_1 & L_2 , Then

① If L_1 & L_2 intersect exactly at one point

Then there is a unique solution.

② If L_1 & L_2 are coincident Then there are infinity many solution.

③ If L_1 & L_2 are parallel Then there is No-solution.

e.g. solve the linear eq.

$$x - y = 1 \quad ①$$

$$2x + y = 6 \quad ②$$

$$3x = 7$$

$$\boxed{x = \frac{7}{3}}$$

$$\boxed{y = \frac{4}{3}}$$

There is a unique solution

$$\left(\frac{7}{3}, \frac{4}{3} \right)$$

Ex. solve the linear eq.

$$\begin{aligned} x + y &= 4 \\ 3x + 3y &= 6 \end{aligned}$$

The given system of eq. has no solution

* Gauss Elimination

Q. Use Gauss Elimination to solve the system of linear eq.

$$x_1 + 5x_2 = 7$$

$$-2x_1 - 7x_2 = -5$$

Soln: write the augmented Matrix of eqn ① & ②

$$\left[\begin{array}{cc|c} 1 & 5 & 7 \\ -2 & -7 & -5 \end{array} \right]$$

Now using Elementary Row Transformations convert it into Row-Echelon form.

$$\left[\begin{array}{ccc|c} 1 & 5 & 7 & \\ 0 & -1 & 3 & \end{array} \right] R_2 \rightarrow R_2 + 2R_1$$

$$\left[\begin{array}{ccc|c} 1 & 0 & -8 & 7 - 5(3) \\ 0 & 1 & 3 & \end{array} \right] R_1 \rightarrow R_1 + 5R_2$$

This is The Row-Echelon form

$$x_1 = -8 \quad x_2 = 3$$

Q2 Solve the system of linear equation.

$$\begin{aligned}x - 3y + z &= 4 \\2x - 8y + 8z &= -2 \\-6x + 3y - 15z &= 9.\end{aligned}$$

$$\left[\begin{array}{cccc} 1 & -3 & 1 & 4 \\ 2 & -8 & 8 & -2 \\ -6 & 3 & -15 & 9 \end{array} \right] \rightarrow \left[\begin{array}{cccc} 1 & -3 & 1 & 4 \\ 0 & -2 & 6 & -10 \\ -6 & 3 & -15 & 9 \end{array} \right] \Rightarrow \left[\begin{array}{cccc} 1 & -3 & 1 & 4 \\ 0 & -2 & 6 & -10 \\ 0 & -15 & -12 & 21 \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{cccc} 1 & -3 & 1 & 4 \\ 0 & 1 & -3 & 5 \\ 0 & -15 & -12 & 21 \end{array} \right] \Rightarrow \left[\begin{array}{cccc} 1 & -3 & 1 & 4 \\ 0 & 1 & -3 & 5 \\ 0 & 0 & 18 & -54 \end{array} \right] \Rightarrow \left[\begin{array}{cccc} 1 & -3 & 1 & 4 \\ 0 & 1 & -3 & 5 \\ 0 & 0 & 1 & -3 \end{array} \right]$$

75
21
34

$$\Rightarrow \left[\begin{array}{ccc} 1 & 0 & -8 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{array} \right] \Rightarrow \left[\begin{array}{cccc} 1 & 0 & 0 & -5 \\ 0 & 1 & 0 & -4 \\ 0 & 0 & 1 & -3 \end{array} \right]$$

$$\left[\begin{array}{ccc} 1 & -3 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & -1 \end{array} \right] \text{ Check } \left[\begin{array}{c} 4 \\ -5 \\ 2 \end{array} \right]$$

Now using Back substitution, we can find the value of x, y, z

here $-z = 2$
 $\underline{\underline{z = -2}}$

$$\left| \begin{array}{l} -y + 3z = -5 \\ y = 5 + 3z \\ y = 5 + (-6) \\ \boxed{y = -1} \end{array} \right. \quad \left| \begin{array}{l} x - 3y + z = 4 \\ x = 4 - 2 + 3y \\ x = 4 + 2 - 3 \\ = \cancel{8} - 3 \\ \boxed{x = 3} \end{array} \right.$$

Matrix Properties:

- (a) $A+B = B+A$ commutative law for addition
- (b) $A+(B+C) = (A+B)+C$ associative law for addition
- (c) $A(BC) = (AB)C$ associative law for multiplication

Note: In matrix $AB \neq BA$

Ex. consider $A = \begin{bmatrix} -1 & 0 \\ 2 & 3 \end{bmatrix}$ & $B = \begin{bmatrix} 1 & 2 \\ 3 & 0 \end{bmatrix}$

$$AB = \begin{bmatrix} -1 & -2 \\ 11 & 4 \end{bmatrix}, \quad BA = \begin{bmatrix} 3 & 6 \\ -3 & 0 \end{bmatrix}$$

$$AB \neq BA$$

Zero Matrix is denoted by 0 for ex

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}_{2 \times 2}, \quad \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}_{1 \times 3}, \quad \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}_{3 \times 1}$$

Identity Matrix an $n \times n$ matrix with ones on the main diagonal & zero else. wher

Ex. $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Invertible (no-singular): If $AB = BA = I$, then I is invertible.

Ex.: $A = \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix}$ & $B = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}$

$$AB = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I, \quad BA = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

Theorem 1.4.5 Inverse

In the matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is invertible iff $ad-bc \neq 0$

Then the formula is

$$A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Q: Find the inverse

$$(a) A = \begin{bmatrix} 6 & 1 \\ 5 & 2 \end{bmatrix}$$

$$(b) B = \begin{bmatrix} -1 & 2 \\ 3 & -6 \end{bmatrix}$$

Sln (a) $(6)(2) - (5)(1) = 12 - 5 = 7$

$$A^{-1} = \frac{1}{7} \begin{bmatrix} 2 & -1 \\ -5 & 6 \end{bmatrix} = \begin{bmatrix} \frac{2}{7} & -\frac{1}{7} \\ -\frac{5}{7} & \frac{6}{7} \end{bmatrix}$$

(b) $(-1)(-6) - (3)(2) = 6 - 6 = 0$

Using Row operation find the inverse

$$A = \begin{bmatrix} 1 & 3 \\ -1 & -7 \end{bmatrix}$$

Sln: We can write $[A|I] = \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ -1 & -7 & 0 & 1 \end{array} \right]$

$$R_2 \rightarrow R_2 + 2R_1 \quad \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & -1 & 2 & 1 \end{array} \right]$$

R2 $\times -1$ $\left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & 1 & -2 & -1 \end{array} \right]$

$$R_1 \rightarrow R_1 - 3R_2 \quad \left[\begin{array}{cc|cc} 1 & 0 & 7 & 3 \\ 0 & 1 & -2 & -1 \end{array} \right]$$

$$A^{-1} = \left[\begin{array}{cc} 7 & 3 \\ -2 & -1 \end{array} \right]$$

Ex. Using Row operation find A^{-1}

$$A = \left[\begin{array}{ccc} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{array} \right]$$

$$[A|I] = \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 2 & 5 & 3 & 0 & 1 & 0 \\ 1 & 0 & 8 & 0 & 0 & 1 \end{array} \right]$$

$$R_2 \rightarrow R_2 - 2R_1 \quad \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & -2 & 5 & -1 & 0 & 1 \end{array} \right]$$

$$R_3 \rightarrow R_3 + 2R_2 \quad \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & -1 & -5 & 2 & 1 \end{array} \right]$$

$$R_3 \times -ve \quad \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & 1 & 5 & -2 & 1 \end{array} \right]$$

$$R_1 \rightarrow R_1 - 3R_3 \quad \left[\begin{array}{ccc|ccc} 1 & 2 & 0 & -14 & 6 & 3 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & 5 & -2 & 1 \end{array} \right]$$

$$R_2 \rightarrow R_2 + 3R_3 \quad \left[\begin{array}{ccc|ccc} 1 & 2 & 0 & -14 & 6 & 3 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & 5 & -2 & 1 \end{array} \right]$$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -40 & 16 & 19 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{array} \right]$$

Theorem 1.6.3

if A is invertible $n \times n$ matrix, then for each $n+1$ matrix b , the system for each $n+1$ matrix b , The system of equation $A\bar{x} = b$ has exactly one solution $\bar{x} = A^{-1}b$

ex. Find the solution of system of linear eq.
using A^{-1}

$$x + 3y = 1$$

$$2x + 5y = 3$$

we can write $[A|I] = \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 2 & 5 & 0 & 1 \end{array} \right]$

$$R_2 \rightarrow R_2 - 2R_1$$

$$\left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & -1 & -2 & 1 \end{array} \right]$$

$$R_2 \leftarrow -R_2$$

$$\left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & 1 & 2 & -1 \end{array} \right]$$

$$R_1 \rightarrow R_1 - 3R_2$$

$$\left[\begin{array}{cc|cc} 1 & 0 & -5 & 3 \\ 0 & 1 & 2 & -1 \end{array} \right]$$

$$A^{-1} = \left[\begin{array}{cc} -5 & 3 \\ 2 & -1 \end{array} \right], \quad x = A^{-1}b = \left[\begin{array}{cc} -5 & 3 \\ 2 & -1 \end{array} \right] \left[\begin{array}{c} 1 \\ 3 \end{array} \right] = \left[\begin{array}{c} 4 \\ -1 \end{array} \right]$$

$$(x = 4, y = -1)$$

Chapter 2

Determinants

Minors & cofactor: if A is a square matrix the
the minor of a_{ij} is denoted by M_{ij}
The number $(-1)^{i+j} M_{ij}$ is denoted C_{ij} is
called the cofactor of a_{ij} .

Ex: Find the minors & cofactor of

$$A = \begin{bmatrix} 3 & 1 & -4 \\ 2 & 5 & 6 \\ 1 & 4 & 8 \end{bmatrix}$$

Soln. the minor of a_{11} is $M_{11} = \begin{vmatrix} 5 & 6 \\ 4 & 8 \end{vmatrix} = 16$

the cofactor of a_{11} is

$$C_{11} = (-1)^{1+1} M_{11} = (-1)^1 (16) = 16$$

the minor of a_{12} is $M_{12} = \begin{vmatrix} 2 & 6 \\ 1 & 8 \end{vmatrix} = 10$

the cofactor of a_{12} is

$$C_{12} = (-1)^{1+2} M_{12} = (-1)^2 (10) = -10$$

simillary the minor of a_{13} is $M_{13} = \begin{vmatrix} 2 & 5 \\ 1 & 4 \end{vmatrix} = 3$

and the cofactor $C_{13} = (-1)^{1+3} M_{13} = (-1)^4 (3) = 3$

$$M_{32} = \begin{vmatrix} 3 & -4 \\ 2 & 6 \end{vmatrix} = 26 \quad C_{32} = (-1)^{2+3} M_{23} = (-1)^5 (26) = -26$$

cofactor

Cofactor expansion Along Row wise:

Ex. Find the determinant by cofactor expansion along first Row then first column.

$$A = \begin{bmatrix} 3 & 1 & 0 \\ -2 & -4 & 3 \\ 5 & 4 & -2 \end{bmatrix}$$

Soln.

(a)

$$\det(A) = 3 \begin{vmatrix} -4 & 3 \\ 4 & -2 \end{vmatrix} - 1 \begin{vmatrix} 2 & 3 \\ 5 & -2 \end{vmatrix} + 0 \begin{vmatrix} 2 & -4 \\ 5 & 4 \end{vmatrix}$$

$$= 3(-4) - 1(-1) + 0 = -12 + 1 = -1$$

$$(b) \quad \det(A) = 3 \begin{vmatrix} -4 & 3 & 1 \\ 4 & -2 & -2 \\ 5 & -2 & 1 \end{vmatrix} + 5 \begin{vmatrix} 1 & 0 & 0 \\ 4 & -2 & 1 \\ 5 & -2 & 3 \end{vmatrix}$$

$$= 3(-4) + 2(-2) + 5(3) = -12 - 4 + 15 = -1$$

Technique to evaluate 2×2 and 3×3 matrix

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \text{ and } \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\begin{array}{ccc|cc} a_{11} & a_{12} & a_{13} & a_{11} & a_{12} \\ a_{21} & a_{22} & a_{23} & a_{21} & a_{22} \\ a_{31} & a_{32} & a_{33} & a_{31} & a_{32} \end{array}$$

$$\begin{aligned} &= a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} \\ &\quad - a_{13}a_{22}a_{31} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33} \end{aligned}$$

$$\text{Ex. Calculate } A = \left| \begin{array}{ccc|cc} 1 & 5 & -3 & 1 & 5 \\ 1 & 0 & 2 & 1 & 0 \\ 3 & -1 & 2 & 3 & -1 \end{array} \right|$$

$$= (1)(0)(2) + (5)(2)(3) + (-3)(1)(-1) \\ - (-3)(0)(3) - (1)(2)(-1) - (5)(1)(2)$$

$$= 0 + 30 + 3 + 0 + 2 - 10 = 25$$

Theorem 2.2.5 if A is a square matrix with two proportional Rows or two proportional columns then $\det(A) = 0$

ex.

$$\left| \begin{array}{cccc|c} 1 & 3 & -2 & 4 & \\ 1 & 6 & -4 & 8 & R_2 \rightarrow R_2 - 2R_1 \\ 3 & 9 & 1 & 5 & \\ 1 & 1 & 4 & 8 & \end{array} \right|$$

$$\left| \begin{array}{cccc|c} 1 & 3 & -2 & 4 & \\ 0 & 0 & 0 & 0 & \\ 3 & 9 & 1 & 5 & \\ 1 & 1 & 4 & 8 & \end{array} \right|$$

Q. Evaluate the determinate by Row Reduction.

In this we convert the determinant into upper triangular matrix using Row operation.

Q. Evaluate $\text{Det}(A) = \begin{vmatrix} 0 & 1 & 5 \\ 3 & -6 & 9 \\ 2 & 6 & 1 \end{vmatrix}$

$R_2 \leftrightarrow R_1, A = - \begin{vmatrix} 3 & -6 & 9 \\ 0 & 1 & 5 \\ 2 & 6 & 1 \end{vmatrix}$

take common 3 = $-3 \begin{vmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 2 & 6 & 1 \end{vmatrix}$

$R_3 \rightarrow R_3 - 2R_1 = -3 \begin{vmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 0 & 10 & -5 \end{vmatrix}$

$R_3 \rightarrow R_3 - 10R_2 = -3 \begin{vmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 0 & 0 & -55 \end{vmatrix}$

~~$R_3 \rightarrow R$~~

$= (-3)(-55) \begin{vmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{vmatrix}$

$= (-3)(-55)(1)$

$= 165$

Theorem 2.3.3

A square matrix A is invertable
iff $\det A \neq 0$

Theorem: if A & B a square matrix of
the same size

$$\text{then } \det(A \cdot B) = \det(A) \cdot \det(B)$$

Cramers Rule: If $Ax = b$ is a system of
 n -linear equation in n unknowns such
that $\det(A) \neq 0$,
then the system has a unique
solution, this solutions is

$$x_1 = \frac{\det(A_1)}{\det(A)}, \quad x_2 = \frac{\det(A_2)}{\det(A)} \dots \quad x_n = \frac{\det(A_n)}{\det(A)}$$

where $A_1 = \begin{vmatrix} b_1 & a_{12} & a_{13} \\ b_2 & a_{21} & a_{23} \\ b_3 & a_{31} & a_{33} \end{vmatrix}$ $A_2 = \begin{vmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{vmatrix}$

$$A_3 = \begin{vmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ a_{31} & a_{32} & b_3 \end{vmatrix}$$

Q: Using cramers Rule to solve

$$\begin{array}{rcl} x_1 + 2x_3 = 6 \\ -3x_1 + 4x_3 = 30 \\ -x_1 - 2x_1 + 3x_3 = 8 \end{array}$$

$$A = \begin{bmatrix} 1 & 0 & 2 \\ -3 & 4 & 6 \\ -1 & -2 & 3 \end{bmatrix}, \quad A_1 = \begin{bmatrix} 6 & 0 & 2 \\ 30 & 4 & 6 \\ 8 & -2 & 3 \end{bmatrix}$$

$$A_2 = \begin{bmatrix} 1 & 6 & 2 \\ -3 & 30 & 6 \\ -1 & 8 & 3 \end{bmatrix}, \quad A_3 = \begin{bmatrix} 1 & 0 & 6 \\ -3 & 4 & 30 \\ -1 & -2 & 8 \end{bmatrix}$$

$$\det(A) = 44, \quad \det(A_1) = -40 \\ \det(A_2) = 72, \quad \det(A_3) = 152$$

$$x_1 = \frac{\det(A_1)}{\det(A)} = \frac{-40}{44} = \frac{-80}{88} = \frac{10}{11}$$

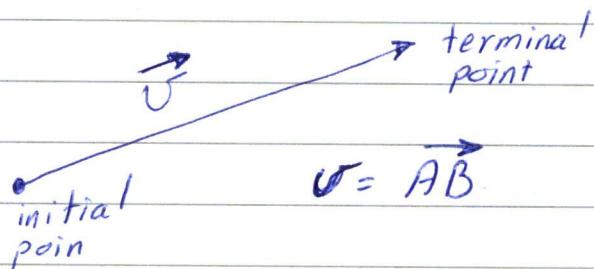
$$x_2 = \frac{\det(A_2)}{\det(A)} = \frac{72}{44} = \frac{18}{11}$$

$$x_3 = \frac{\det(A_3)}{\det(A)} = \frac{152}{44} = \frac{38}{11}$$

Chapter 3

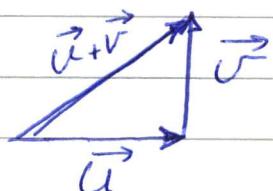
Vectors

Vector can be represent in 2-D or 3-D



zero vector is denoted by $\vec{0}$, in 2-D $\vec{0} = (0,0)$
and 3-D $\vec{0} = (0,0,0)$

Addition:



component of the vector:

if we have 2 vectors $P_1(x_1, y_1)$ and $P_2(x_2, y_2)$,
Then component of vectors is given by
 $\vec{P_1 P_2} = (x_2 - x_1, y_2 - y_1)$

Q: Find the component of a vector
with initial point $P_1(2, -1, 4)$ & terminal point $P_2(7, 5, -8)$

$$\vec{P_1 P_2} = (7-2, 5-(-1), -8-4) = (5, 6, -12)$$

Q: if $\vec{v} = (1, -3, 2)$ & $\vec{w} = (4, 2, 1)$

find $\vec{v} + \vec{w}$ & $\vec{v} - \vec{w}$

$$\vec{v} + \vec{w} = (1+4, -3+2, 2+1) = (5, -1, 3)$$

$$\vec{v} - \vec{w} = (1-4, -3-2, 2-1) = (-3, -5, 1)$$

Theorem 3.1 if $\vec{v}, \vec{u}, \vec{w}$ are the vectors in \mathbb{R}^n & if k, m are scalars, then

$$(a) \vec{u} + \vec{v} =$$

$$(b) (\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w})$$

$$(c) \vec{u} + 0 = 0 + \vec{u} = \vec{u}$$

$$(d) k(\vec{u} + \vec{w}) = k\vec{u} + k\vec{w}$$

$$(e) 0 \cdot \vec{v} = 0$$

$$(f) k \cdot 0 = 0$$

$$(g) 1 \cdot \vec{u} = \vec{u}$$

Norm of vector

The length of a vector is defined by $\|\vec{v}\|$ which is called the norm of \vec{v} or length of \vec{v}

$$\text{in } \mathbb{R}^2 \quad \|\vec{v}\| = \sqrt{\vec{v}_1^2 + \vec{v}_2^2}$$

$$\text{in } \mathbb{R}^3 \quad \|\vec{v}\| = \sqrt{\vec{v}_1^2 + \vec{v}_2^2 + \vec{v}_3^2}$$

Q: Find the norm of a vector $v = (-3, 2, 1)$ in \mathbb{R}^3

$$\|\vec{v}\| = \sqrt{(-3)^2 + (2)^2 + (1)^2} = \sqrt{9+4+1} = \sqrt{14}$$

Unit vector ~~\vec{u}~~ $\vec{u} = \frac{1}{\|\vec{v}\|} \vec{v}$

standard unit vector in \mathbb{R}^2 or in \mathbb{R}^3

$$\text{in } \mathbb{R}^2 \quad i = (1, 0) \quad \& \quad j = (0, 1)$$

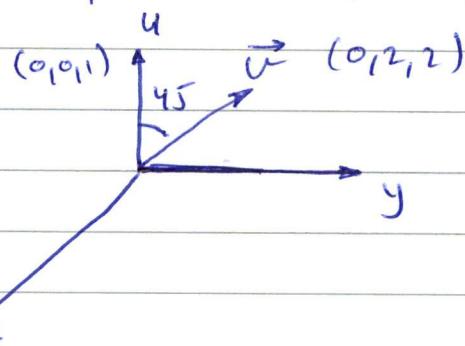
$$\text{in } \mathbb{R}^3 \quad i = (1, 0, 0), \quad j = (0, 1, 0) \quad \& \quad k = (0, 0, 1)$$

Dot Product: If θ is the angle between \vec{u} & \vec{v} , Then

$$\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$$

$$\text{or } \cos \theta = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|}$$

Q: Find the dot product of figure:



$$\|\vec{u}\| = \sqrt{(0)^2 + (0)^2 + (1)^2} = 1$$

$$\|\vec{v}\| = \sqrt{(0)^2 + (2)^2 + (2)^2} = \sqrt{8} = 2\sqrt{2}$$

$$\cos \theta = \cos 45^\circ = \frac{1}{\sqrt{2}}$$

$$\text{Now } \vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta = (1)(2\sqrt{2}) \frac{1}{\sqrt{2}} = 2$$

Q: Find the dot product of $a = (1, 2, 3)$ & $b = (4, -5, 6)$

$$\begin{aligned} \vec{a} \cdot \vec{b} &= a_1 b_1 + a_2 b_2 + a_3 b_3 = (1)(4) + (2)(-5) + (3)(6) \\ &= 4 - 10 + 18 = 12 \end{aligned}$$

Q: if $a = (6, -1, 3)$ for what value of c is the vector $b = (4, c, -2)$ perpendicular to a

$$a \cdot b = 24 + (-1)c - 6 = 18 - c$$

perpendicular $\rightarrow \cos 90^\circ = 0$

$$c = 18 \quad \leftarrow a \cdot b = 0 = 18 - c$$

Orthogonality: Two vectors are orthogonal

iff $\vec{u} \cdot \vec{v} = 0$

Q: Show that $\vec{u} = (-2, 3, 1, 4)$ and $\vec{v} = (1, 2, 0, -1)$ are orthogonal in \mathbb{R}^4

Theorem if $a \neq b$ are constant & non-zero

Then equation of the form

$$ax + by + c = 0$$

represent a line in \mathbb{R}^2 with normal
 $a \neq b$.

Theorem 3.3.4

In \mathbb{R}^2 the distance between the point $P_0(x_0, y_0)$ and the line $ax + by + c = 0$

$$\text{is } D = \frac{|ax_0 + by_0 + c|}{\sqrt{a^2 + b^2}}$$

similarly in \mathbb{R}^3

$$D = \frac{|ax_0 + by_0 + cz_0 + d|}{\sqrt{a^2 + b^2 + c^2}}$$

Q: Find the distance between the point $(1, -4, -3)$ and the plane $2x - 3y + 6z = -1$

$$2x - 3y + 6z + 1 = 0$$

$$D = \frac{|(2)(1) + (-3)(-4) + (6)(-3) + 1|}{\sqrt{(2)^2 + (-3)^2 + (6)^2}} = \frac{|2 + 12 - 18 + 1|}{\sqrt{49}} = \frac{|-3|}{7} = \frac{3}{7}$$

Q: Two planes are given $x + 2y - 2z = 3$ & $2x + 4y - 4z = 7$
Find the distance between them.

or we can write

$$x + 2y - 2z - 3 = 0 \quad \textcircled{1}$$

$$2x + 4y - 4z - 7 = 0 \quad \textcircled{2}$$

put in \textcircled{1} $y = z = 0 \rightarrow x = 3$

point is $(3, 0, 0)$

$$D = \frac{|(3)(2) + (4)(0) + (-4)(0) + (-7)|}{\sqrt{(2)^2 + (4)^2 + (-4)^2}} = \frac{|6 - 7|}{\sqrt{36}} = \frac{|-1|}{6} = \frac{1}{6}$$

Defination If $x_0 \in \vec{v}$ are vectors in \mathbb{R}^n and if \vec{v} is non-zero,

Then : the equation $x = x_0 + t\vec{v}$ defines a line through x_0 . That is parallel to \vec{v} similarly \mathbb{R}^3

$$x = x_0 + t_1 u_1 + t_2 u_2$$

Q: Find a vector equation & parametric equation of line in \mathbb{R}^3 that pass through the point $P_0(1, 2, -3)$ & is parallel the vector $u = (4, -5, 1)$

we know the eq. of the line $x = x_0 + t\vec{u}$
here $x_0 = (1, 2, -3)$ $u = (4, -5, 1)$

$$(x, y, z) = (1, 2, -3) + t(4, -5, 1)$$

$$x = 1 + 4t$$

$$y = 2 - 5t$$

$$z = -3 + t$$

3.5 Cross Product

if $\vec{u} = (u_1, u_2, u_3)$, $\vec{v} = (\vec{v}_1, v_2, v_3)$

cros product $\vec{u} \times \vec{v} =$

$$= (u_2 v_3 - u_3 v_2, u_3 v_1 - u_1 v_3, u_1 v_2 - u_2 v_1)$$

$$\begin{bmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{bmatrix} \Rightarrow \vec{u} \times \vec{v}$$

$$\hookrightarrow \left(\begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} - \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} + \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} \right)$$

Q: Calculate the cross product

$$\vec{u} = (1, 2, -2), \quad \vec{v} = (3, 0, 1) \quad \begin{bmatrix} 1 & 2 & -2 \\ 3 & 0 & 1 \end{bmatrix}$$

$$\vec{u} \times \vec{v} = (1^2 - 2^2, 1 - 3, 1 + 3) = (-3, -2, 4)$$

$$= (-3, -2, 4)$$

chap 4 Vector Spaces

- 1. A vector space is a set of vectors that satisfies certain properties under addition and scalar multiplication.
- 2. The properties of a vector space are closure under addition, closure under scalar multiplication, associativity of addition, commutativity of addition, the existence of an additive identity (zero vector), and the existence of additive inverses.
- 3. A subspace is a subset of a vector space that is itself a vector space under the same operations.
- 4. A basis for a vector space is a linearly independent set of vectors that spans the space.
- 5. The dimension of a vector space is the number of vectors in any basis for the space.
- 6. A linear transformation is a function that maps a vector space to another vector space, preserving the operations of addition and scalar multiplication.
- 7. The kernel of a linear transformation is the set of all vectors in the domain that map to the zero vector in the codomain.
- 8. The range of a linear transformation is the set of all vectors in the codomain that are images of vectors in the domain.
- 9. The rank-nullity theorem states that for a linear transformation $T: V \rightarrow W$, the dimension of the domain is equal to the sum of the dimension of the kernel and the dimension of the range.
- 10. A matrix is a rectangular array of numbers, used to represent linear transformations between vector spaces.
- 11. Matrix multiplication represents the composition of linear transformations.
- 12. The inverse of a matrix, if it exists, represents the inverse of a linear transformation.
- 13. Determinants are scalar values associated with square matrices, used to determine if a matrix is invertible.
- 14. Eigenvalues and eigenvectors are scalar values and vectors, respectively, that represent the scaling factor by which a linear transformation acts on specific vectors.
- 15. Diagonalization is the process of finding a diagonal matrix that is similar to a given matrix, representing the matrix in a basis where it is represented by a simple scaling matrix.
- 16. Orthogonality is a relationship between vectors where their dot product is zero.
- 17. Orthonormal basis is a basis for a vector space where the basis vectors are orthogonal and have unit length.
- 18. Gram-Schmidt process is a method for finding an orthonormal basis for a subspace of a vector space.
- 19. Inner product is a generalization of the dot product that allows for the calculation of the angle between vectors and the projection of one vector onto another.
- 20. Norm is a measure of the length or magnitude of a vector.

Row Space, column space & Null space

Let the matrix $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & & & & \\ a_{m1} & a_{m2} & \cdots & & a_{mn} \end{bmatrix}$

The vectors $r_1 = [a_{11}, a_{12}, a_{13}, \dots, a_{1n}]$

$r_2 = [a_{21}, a_{22}, \dots, a_{2n}]$

\vdots

r_m

are called the Row vector

and the vectors

$$\begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}, \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix}, \dots$$

are called the column vector.

Q: Let $A = \begin{bmatrix} 2 & 1 & 0 \\ 3 & -1 & 4 \end{bmatrix}$

$$r_1 = [2 \ 1 \ 0], r_2 = [3 \ -1 \ 4]$$

$$c_1 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, c_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, c_3 = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

Row Space The subspace of R^n spanned by Row vectors of A is called the Row space.

Column Space //

Null space: The solution space of $Ax = 0$ where is the subspace of R^n is called the null space of A.

Q: Find the basis for Row and column space

$$A = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 \\ 2 & -6 & 9 & -1 & 8 & 2 \\ 2 & -6 & 9 & -1 & 9 & 7 \\ 1 & 3 & -4 & 2 & -5 & -4 \end{bmatrix}$$

Soln. Reduced to Row echelon form

$$R = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 \\ 0 & 0 & 1 & 3 & -2 & -6 \\ 0 & 0 & 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The basis vector are (non zero Row)

$$r_1 = [1 \quad -3 \quad 4 \quad -2 \quad 5 \quad 4]$$

$$r_2 = [0 \quad 0 \quad 1 \quad 3 \quad -2 \quad -6]$$

$$r_3 = [0 \quad 0 \quad 0 \quad 0 \quad 1 \quad 5]$$

Now we observe that first, third, fifth column contains the leading 1. so

$$C_1' = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, C_3' = \begin{bmatrix} 4 \\ 1 \\ 0 \\ 0 \end{bmatrix}, C_5' = \begin{bmatrix} 5 \\ -2 \\ 1 \\ 0 \end{bmatrix}$$

$$C_1 = \begin{bmatrix} 1 \\ 2 \\ 2 \\ 1 \end{bmatrix}, C_3 = \begin{bmatrix} 4 \\ 9 \\ 9 \\ -4 \end{bmatrix}, C_5 = \begin{bmatrix} 5 \\ 8 \\ 9 \\ -5 \end{bmatrix}$$

Q: The matrix $R = \begin{bmatrix} 1 & -2 & 5 & 0 & 3 \\ 0 & 1 & 3 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

Soln. this is already in Row echelon form

$$r_1 = [1 \quad -2 \quad 5 \quad 0 \quad 3]$$

$$r_2 = [0 \quad 1 \quad 3 \quad 0 \quad 0]$$

$$r_3 = [0 \quad 0 \quad 0 \quad 1 \quad 0]$$

2 $C_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, C_2 = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, C_4 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$

Q: Find the basis for the Row space:

$$A = \begin{bmatrix} 1 & -2 & 0 & 0 & 3 \\ 2 & -5 & -3 & -2 & 6 \\ 0 & 5 & 15 & 10 & 0 \\ 2 & 6 & 18 & 8 & 6 \end{bmatrix}$$

Soln.

$$A^T = \begin{bmatrix} 1 & 2 & 0 & 2 \\ -2 & -5 & 5 & 6 \\ 0 & -3 & 15 & 18 \\ 0 & -2 & 10 & 8 \\ 3 & 6 & 0 & 6 \end{bmatrix}$$

convert it into Row echelon form.

$$A^T = \begin{bmatrix} 1 & 2 & 0 & 2 \\ 0 & 1 & -5 & -10 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$C_1' = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad C_2' = \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad C_4' = \begin{bmatrix} 2 \\ -10 \\ 1 \\ 0 \end{bmatrix}$$

$$C_1 = \begin{bmatrix} 1 \\ -2 \\ 0 \\ 0 \\ -3 \end{bmatrix}, \quad C_2 = \begin{bmatrix} 2 \\ -5 \\ -3 \\ -2 \\ 6 \end{bmatrix}, \quad C_4 = \begin{bmatrix} 2 \\ 6 \\ 18 \\ 8 \\ 6 \end{bmatrix}$$

$$r_1 = [1 \ -2 \ 0 \ 0 \ 3]$$

$$r_2 = [2 \ -5 \ -3 \ -2 \ 6]$$

$$r_4 = [2 \ 6 \ 18 \ 8 \ 6]$$

Rank & Nullity

The common dimension of the row space & column space of the matrix A is called the Rank of A.

The dimension of the null space of A is called the nullity (A)

Q: Find the rank & nullity of matrix

$$A = \begin{bmatrix} -1 & 2 & 0 & 4 & 5 & -3 \\ 3 & -7 & 2 & 0 & 1 & 4 \\ 2 & -5 & 2 & 4 & 6 & 1 \\ 4 & -9 & 2 & -4 & -4 & 7 \end{bmatrix}$$

Soln: Using Row echelon form

$$A = \begin{bmatrix} 1 & 0 & -4 & -28 & -37 & 13 \\ 0 & 1 & -2 & -12 & -16 & 5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

the rank of A is 2 because non zero is 2

(No. of non-zero Row)

Now we have 4 equation 6 unknown

Dimension Theorem :

$$\text{Rank}(A) + \text{nullity}(A) = n - \text{number of column}$$

we know, by Rank Nullity theorem

$$\begin{aligned}\text{Rank}(A) + \text{Nullity}(A) &= n \\ 2 + \text{Nullity}(A) &= 6\end{aligned}$$

$$\begin{aligned}\text{Nullity}(A) &= 6 - 2 \\ &= 4\end{aligned}$$

Q: let $A = \begin{bmatrix} 1 & 0 & -2 & 1 & 0 \\ 0 & -1 & -3 & 1 & 3 \\ -2 & -1 & 1 & -1 & 3 \\ 0 & 3 & 9 & 0 & -12 \end{bmatrix}$

- Find the Rank & Nullity of A
- Find a subset of the column vectors of that form a basis for the column space of A

a)

$$A = \begin{bmatrix} 1 & 0 & -2 & 0 & 1 \\ 0 & 1 & 3 & 0 & -4 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{Rank}(A) = 3$$

$$\text{Nullity}(A) = n - \text{Rank}(A) = 5 - 3 = 2$$

b)

$$c_1' = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad c_2' = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad c_3' = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$c_1 = \begin{bmatrix} 1 \\ 0 \\ -2 \\ 0 \end{bmatrix}, \quad c_2 = \begin{bmatrix} 0 \\ -1 \\ -1 \\ 3 \end{bmatrix}, \quad c_4 = \begin{bmatrix} 1 \\ 1 \\ -1 \\ 0 \end{bmatrix}$$

Chapter 5

Eigen Value & Eigen Vector

Defn:

Let A be a square matrix, and λ be any value.

Then $Ax = \lambda x \rightarrow \textcircled{1}$

has a ~~non-solution~~ non-trivial solution are called Eigen Value of A .

Corresponding to Eigen value λ , \exists a non-zero vector x , such that

$|\lambda I - A| x = 0$, Then x is called The Eigen Vector

Remark: ① $|\lambda I - A| = 0$ is called the characteristic equation.

② The Eigen value of triangular matrix are its diagonal elements

Ex. Determine the Eigen Value and the Eigen Vectors

of $\begin{bmatrix} 3 & 1 \\ 6 & 2 \end{bmatrix}$

Step 1: The characteristic equation of A is given by $|\lambda I - A| = 0$

$$|\lambda I - A| = \begin{vmatrix} \lambda - 3 & -1 \\ -6 & \lambda - 2 \end{vmatrix} = 0$$

$$= (\lambda - 3)(\lambda - 2) - 6 = 0$$

$$\lambda^2 - 5\lambda + 6 - 6 = 0$$

$$\lambda(\lambda - 5) = 0$$

$$\boxed{\lambda = 0, 5}$$

$\lambda_1 = 0, \lambda_2 = 5$ are Eigen values of A.

Step 2: To find the Eigen vectors:

(a) corresponding $\lambda_1 = 0$

$$(\lambda_1 I - A) X = 0$$

$$\begin{pmatrix} 0-3 & -1 \\ -6 & 0-2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$\begin{pmatrix} -3 & -1 \\ -6 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$\underline{-3x_1 - x_2 = 0} \rightarrow ①$$

$$-6x_1 - 2x_2 = 0 \rightarrow ②$$

since the rank of matrix is one.

so we choose eqn ①

$$-x_2 = 3x_1$$

$$x_2 = -3x_1$$

or we can write

$$= \{(x_1, -3x_1) \in \mathbb{A} | x_1 \text{ is scalar}\}$$

$$= \{x(1, -3) \in \mathbb{A} | x, \text{ is scalar}\}$$

(1, -3) are the Eigen vector

(b) Eigen vector corresponding $\lambda_2 = 5$

$$(\lambda_2 I - A)x = 0$$

$$\begin{pmatrix} 5-3 & -1 \\ -6 & 5-2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$\begin{pmatrix} 2 & -1 \\ -6 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$2x_1 - x_2 = 0 \rightarrow ①$$

$$-6x_1 + 3x_2 = 0 \rightarrow ②$$

since the Rank of the matrix is one. so
so we choose eq ①

$$2x_1 = x_2$$

$$= \{ (x_1, 2x_1) \in V \mid x_1 \text{ is scalar} \}$$

$$= \{ x(1, 2) \in V \mid x_1 \text{ is scalar} \}$$

(1, 2) are the Eigen vector vectors.

Ex. Find the Eigen value of $A = \begin{bmatrix} 3 & 0 \\ -8 & -1 \end{bmatrix}$

The characteristic equation is:

$$|\lambda I - A| = 0$$

$$\Rightarrow \begin{vmatrix} \lambda - 3 & 0 \\ -8 & \lambda + 1 \end{vmatrix} = 0$$

\Downarrow
 $\lambda - (-1)$

$$\underbrace{(\lambda - 3)(\lambda + 1)}_{\lambda^2 - 3\lambda + 2 - 3\lambda - 3 = 0} + 0 = 0$$

$$\cancel{\lambda^2 - 3\lambda + 2} + \cancel{2\lambda} + \cancel{3} = 0$$

$\lambda = 3, -1 \rightarrow$ the eigen values of A

Ex. Find the Eigen value of $A = \begin{bmatrix} 1/2 & 0 & 0 \\ -1 & 2/3 & 0 \\ 5 & -8 & 1/4 \end{bmatrix}$

Since it is a lower triangle matrix
so the Eigen value its diagonal element

$$\lambda_1 = 1/2, \lambda_2 = 2/3, \lambda_3 = -1/4$$

Ex. Find the Eigen value of $A \begin{bmatrix} -2 & -1 \\ 5 & 2 \end{bmatrix}$

the characteristic eqn.

$$|\lambda I - A| = 0$$

$$\begin{vmatrix} \lambda+2 & +1 \\ -5 & \lambda-2 \end{vmatrix} = 0 \Rightarrow (\lambda+2)(\lambda-2) + 5 = 0$$
$$\lambda^2 + 2\lambda + 2\lambda - 4 + 5 = 0$$
$$\lambda^2 + 4\lambda + 1 = 0$$

$$\lambda^2 + 1 = 0$$

$$\lambda = \pm i$$

Diagonalization :

Step 1: check The E.V. are L.I.

Step 2: Form the matrix $P = [P_1, P_2, \dots]$

Step 3: The matrix $P^{-1}AP$ will be diagonal.

Ex. Find the E.V & E-vector, basis & diagonalise

the matrix $A = \begin{bmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$

Step 1 $|(\lambda I - A)| = 0$

$$\begin{vmatrix} \lambda & 0 & +2 \\ -1 & \lambda-2 & -1 \\ -1 & 0 & \lambda-3 \end{vmatrix} = 0$$

$$\lambda^3 - 5\lambda^2 + 8\lambda - 4 = 0$$

$$(\lambda-1)(\lambda-2)^2 = 0$$

$$\lambda = 1, 2, 2$$

Step 2 E.V corresponding to $\lambda_1 = 1$

$$(\lambda_1 I - A) x = 0$$

$$\begin{pmatrix} 1 & 0 & 2 \\ -1 & 1 & -1 \\ -1 & 0 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

on solving

$$x_1 = -2s, x_2 = s, x_3 = s$$

$(-1, 1, 1) \rightarrow$ the eign vector

E.V. corresponding $\lambda_2 = 2$

$$(\lambda_2 I - A) \cancel{x} = 0$$

$$\begin{pmatrix} 2 & 0 & +2 \\ -1 & 0 & -1 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$(-1, 0, 1)$$

E.V. corresponding $\lambda_3 = 2$

$$(0, 1, 0)$$

$$P_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, P_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, P_3 = \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$$

$$P = \begin{bmatrix} -1 & 0 & -2 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

diagonlise A , we have to write $P^{-1}AP$

$$P^{-1}AP = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 1 & 1 \\ -1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 2 & 0 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 & -2 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Chapter 6

Inner Product Space

Defn: Let u, v, w be vectors in a vector space V , and C any constant.

Then inner product $\langle u, v \rangle$ if it satisfy the following axioms.

Axiom 1: $\langle u, v \rangle = \langle v, u \rangle$

Axiom 2: $\langle u, v+w \rangle = \langle u, v \rangle + \langle u, w \rangle$

Axiom 3: $C \langle u, v \rangle = \langle Cu, v \rangle$

Axiom 4: $\langle u, v \rangle \geq 0$ and $\langle u, v \rangle = 0$ iff $v=0$

Note: A vector space V is $(V, +, \cdot)$ with an inner product is called inner product space $\langle V, +, \cdot, \langle \cdot, \cdot \rangle \rangle$

Q: Let $u = (u_1, u_2)$ and $v = (v_1, v_2)$ be the vectors in \mathbb{R}^2

Verify that the Euclidean Inner Product

$$\langle u, v \rangle = 3u_1v_1 + 2u_2v_2$$

satisfy the four inner product Axioms.

Soln.

Axiom 1: $\langle u, v \rangle = 3u_1v_1 + 2u_2v_2$
 $= 3v_1u_1 + 2v_2u_2 = \langle v, u \rangle$

$$\begin{aligned}
 \text{Axiom 2: } \langle u, v+w \rangle &= 3(u_1 + v_1) w_1 + 2(u_2 + v_2) w_2 \\
 &= 3(u_1 w_1 + v_1 w_1) + 2(u_2 w_2 + v_2 w_2) \\
 &= 3u_1 w_1 + 3v_1 w_1 + 2u_2 w_2 + 2v_2 w_2 \\
 &= (3u_1 w_1 + 2u_2 w_2) + (3v_1 w_1 + 2v_2 w_2) \\
 &= \langle u, w \rangle + \langle v, w \rangle
 \end{aligned}$$

$$\begin{aligned}
 \text{Axiom 3: } \langle cu, v \rangle &= 3(cu_1)v_1 + 2(cu_2)v_2 \\
 &= c(3u_1 v_1 + 2u_2 v_2) \\
 &= c \langle u, v \rangle
 \end{aligned}$$

$$\begin{aligned}
 \text{Axiom 4: } \langle u, v \rangle &= 3(v_1, v_1) + 2(v_2, v_2) \\
 &= 3v_1^2 + 2v_2^2 \geq 0
 \end{aligned}$$

with equality iff $v_1 = v_2 = 0$

Q: Show that the function defined inner product
in \mathbb{R}^2 where $u = (u_1, u_2)$ & $v = (v_1, v_2)$

$$\langle u, v \rangle = u_1 v_1 + 2 u_2 v_2$$

Axiom 1: $\langle u, v \rangle = u_1 v_1 + 2 u_2 v_2$
 $= v_1 u_1 + 2 v_2 u_2$
 $= \langle v, u \rangle$

Axiom 2: $\langle u, v+w \rangle = u_1(v_1 + w_1) + 2 u_2(v_2 + w_2)$
 $= u_1 v_1 + u_1 w_1 + 2 u_2 v_2 + 2 u_2 w_2$
 $= u_1 v_1 + 2 u_2 v_2 + u_1 w_1 + 2 u_2 w_2$
 $= \langle u, v \rangle + \langle u, w \rangle$

Axiom 3: $\langle cu, v \rangle = c(u_1 v_1 + 2 u_2 v_2)$
 $= (cu_1)v_1 + 2(cu_2)v_2$
 $= \langle cu, v \rangle$

Axiom 4: $\langle v, v \rangle = v_1 v_1 + 2 v_2 v_2$
 $= v_1^2 + 2 v_2^2$
if $\langle v, v \rangle = 0 \Rightarrow v_1^2 + v_2^2 = 0$
 $\Rightarrow v_1 = v_2 = 0$

Properties of inner product

$$\textcircled{1} \quad \langle 0, u \rangle = \langle v, 0 \rangle = 0$$

$$\textcircled{2} \quad \langle u+v, w \rangle = \langle u, w \rangle + \langle v, w \rangle$$

$$\textcircled{3} \quad \langle u, cv \rangle = c \langle u, v \rangle$$

$$\textcircled{4} \quad \|u\| = \sqrt{\langle u, u \rangle}$$

\textcircled{5} Distance between u and v

$$d(u, v) = \|u - v\| = \sqrt{\langle u - v, u - v \rangle}$$

\textcircled{6} Angle between two non-zero vectors u and v

$$\cos \theta = \frac{\langle u, v \rangle}{\|u\| \|v\|} \quad 0 < \theta \leq \pi$$

Note: if $u \perp v$ then $\langle u, v \rangle = 0$ orthogonal
if $\|u\| = 1$ then it is called a unit vector

Q. Calculating the inner product
 $\langle u - 2v, 3u + 4v \rangle$

$$= \langle u, 3u + 4v \rangle - \langle 2v, 3u + 4v \rangle$$

$$= \langle u, 3u \rangle + \langle u, 4v \rangle - \langle 2v, 3u \rangle - \langle 2v, 4v \rangle$$

$$= 3\langle u, u \rangle + 4\langle u, v \rangle - 6\langle v, u \rangle - 8\langle v, v \rangle$$

$$= 3\|u\|^2 + 4\langle u, v \rangle - 6\langle v, u \rangle - 8\|v\|^2$$

$$= 3\|u\|^2 + 2\langle u, v \rangle - 8\|v\|^2$$

Q: Show that the following set is an orthogonal basis: orthonormal

$$S = \left\{ \underbrace{\left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0 \right)}_{v_1}, \underbrace{\left(\frac{-\sqrt{2}}{6}, \frac{\sqrt{2}}{6}, \frac{2\sqrt{2}}{3} \right)}_{v_2}, \underbrace{\left(\frac{2}{3}, -\frac{2}{3}, \frac{1}{3} \right)}_{v_3} \right.$$

$$v_1 \cdot v_2 = \frac{1}{\sqrt{2}} \left(\frac{-\sqrt{2}}{6} \right) + \frac{1}{\sqrt{2}} \left(\frac{\sqrt{2}}{6} \right) + 0 \left(\frac{2\sqrt{2}}{3} \right)$$

$$= -\frac{1}{6} + \frac{1}{6} = 0$$

$$v_1 \cdot v_3 = \frac{1}{\sqrt{2}} \left(\frac{2}{3} \right) + \frac{1}{\sqrt{2}} \left(-\frac{2}{3} \right) + 0 \left(\frac{1}{3} \right)$$

$$= \frac{2}{3\sqrt{2}} - \frac{2}{3\sqrt{2}} = 0$$

$$\begin{aligned} \mathbf{v}_2 \cdot \mathbf{v}_3 &= -\frac{\sqrt{2}}{6} \left(\frac{2}{3} \right) + \frac{\sqrt{2}}{6} \left(-\frac{2}{3} \right) + \frac{2\sqrt{2}}{3} \left(\frac{1}{3} \right) \\ &= -\frac{\sqrt{2}}{6} - \frac{\sqrt{2}}{6} + \frac{2\sqrt{2}}{9} = 0 \end{aligned}$$

Now for normal

$$\|\mathbf{v}_1\| = \sqrt{\mathbf{v}_1 \cdot \mathbf{v}_1} = \sqrt{\left(\frac{1}{\sqrt{2}}\right)^2 + \left(\frac{1}{\sqrt{2}}\right)^2 + (0)^2} = 1$$

$$\|\mathbf{v}_2\| = \sqrt{\mathbf{v}_2 \cdot \mathbf{v}_2} = \sqrt{\left(\frac{\sqrt{2}}{6}\right)^2 + \left(\frac{\sqrt{2}}{6}\right)^2 + \left(\frac{2\sqrt{2}}{3}\right)^2} = 1$$

$$\|\mathbf{v}_3\| = \sqrt{\mathbf{v}_3 \cdot \mathbf{v}_3} = \sqrt{\left(\frac{2}{3}\right)^2 + \left(\frac{2}{3}\right)^2 + \left(\frac{1}{3}\right)^2} = 1$$

So S is an orthonormal.

Q: In $P_3(x)$ with inner product $\langle \cdot, \cdot \rangle$

$$\langle P_1, P_2 \rangle = a_0 b_0 + a_1 b_1 + a_2 b_2$$

The standard basis $B = \{1, x, x^2\}$

is orthonormal

$$v_1 = 1 + 0x + 0x^2 \quad v_2 = 0 + x + 0x^2 \quad v_3 = 0 + 0x + x^2$$

$$\|v_1\| = \sqrt{v_1 \cdot v_1} = \sqrt{(1)(1) + 0 \cdot 0 + 0 \cdot 0} = 1$$

$$\|v_2\| = \sqrt{v_2 \cdot v_2} = \sqrt{0 \cdot 0 + (1)(1) + 0 \cdot 0} = 1$$

$$\|v_3\| = \sqrt{v_3 \cdot v_3} = 1$$

Now for orthogonal

$$v_1 \cdot v_2 = (1)(0) + (0)(1) + (0)(0) = 0$$

$$v_1 \cdot v_3 = (1)(0) + (0)(0) + (0)(1) = 0$$

$$v_2 \cdot v_3 = (0)(0) + (1)(0) + (0)(1) = 0$$

So it is an orthonormal.

Chapter 7 Diagonalization of Matrix

Orthogonal Matrix: A square matrix is said to be orthogonal if its transpose is same as its inverse i.e $A^{-1} = A^T$ or $AA^T = I$

Q: Check whether it is orthogonal $A = \begin{bmatrix} 3/7 & 2/7 & 6/7 \\ -6/7 & 3/7 & 2/7 \\ 2/7 & 6/7 & -3/7 \end{bmatrix}$

S. Transpose of A is $A^T = \begin{bmatrix} 3/7 & -6/7 & 2/7 \\ 2/7 & 3/7 & 6/7 \\ 6/7 & 2/7 & -3/7 \end{bmatrix}$

Now $AA^T = \begin{bmatrix} 3/7 & 2/7 & 6/7 \\ -6/7 & 3/7 & 2/7 \\ 2/7 & 6/7 & -3/7 \end{bmatrix} \cdot \begin{bmatrix} 3/7 & -6/7 & 2/7 \\ 2/7 & 3/7 & 6/7 \\ 6/7 & 2/7 & -3/7 \end{bmatrix}$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Orthogonally Diagonalizing of $n \times n$ Symmetric Matrix

Step#1: Find the Eigen Values.

Step#2: Find the Eigen Vectors.

Step#3: Find P where $P = [P_1, P_2, P_3]$

such that

$$P^TAP = \begin{bmatrix} a_1 & 0 & 0 \\ 0 & a_2 & 0 \\ 0 & 0 & a_3 \end{bmatrix}$$

Q: Find an orthogonal Matrix P that diagonalize

$$A = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 4 & 2 \\ 2 & 2 & 4 \end{bmatrix}$$

S₁ Step #1: $|2I - A| = 0$

$$|2I - A| = \begin{bmatrix} 2-4 & -2 & -2 \\ -2 & 2-4 & -2 \\ -2 & -2 & 2-4 \end{bmatrix}$$
$$= (\lambda-2)^2(\lambda-8) = 0$$

$\lambda = 2, 2, 8$ are the Eigen Values

Step #2: The Eigen Vector corresponding $\lambda = 2, 2$ are

$$U_1 = \begin{bmatrix} \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \text{ and } U_2 = \begin{bmatrix} \frac{-1}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} \\ \frac{2}{\sqrt{6}} \end{bmatrix}$$

and corresponding to $\lambda = 8$

$$U_3 = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}$$

Step #3: Now $P = [P_1, P_2, P_3]$

$$P = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & \frac{2}{\sqrt{2}} & \frac{1}{\sqrt{3}} \end{bmatrix}$$

$$P^T = \begin{bmatrix} \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{-1}{\sqrt{6}} & \frac{-1}{\sqrt{6}} & \frac{2}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix}$$

$$P^T A P = \begin{bmatrix} \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{-1}{\sqrt{6}} & \frac{-1}{\sqrt{6}} & \frac{2}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix} \begin{bmatrix} 4 & 2 & 2 \\ 2 & 4 & 2 \\ 2 & 2 & 4 \end{bmatrix} \begin{bmatrix} \frac{-1}{\sqrt{2}} & \frac{-1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & \frac{2}{\sqrt{2}} & \frac{1}{\sqrt{3}} \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 8 \end{bmatrix}$$

Quadratic Forms:

A homogeneous polynomial of second degree in any number of variables is called a quadratic form for ex.

$$a_1 x_1^2 + a_2 x_2^2 + 2a_3 x_1 x_2 \quad \cancel{+ a_4 x_1 x_2}$$

• $\Rightarrow \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} a_1 & a_3 \\ a_3 & a_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x^T A x$

similarly

$$a_1 x_1^2 + a_2 x_2^2 + a_3 x_3^2 + 2a_4 x_1 x_2 + 2a_5 x_1 x_3 + 2a_6 x_2 x_3$$

Then

$$\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} a_1 & a_4 & a_5 \\ a_4 & a_2 & a_6 \\ a_5 & a_6 & a_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x^T A x$$

Q. Express the quadratic form in Matrix Notation

(a) $2x^2 + 6xy - 5y^2$

(b) $x_1^2 + 7x_2^2 - 3x_3^2 + 4x_1 x_2 - 2x_1 x_3 + 8x_2 x_3$

$$(a) 2x^2 + 6xy - 5y^2 = \begin{bmatrix} xy \\ xy \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 3 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$(b) x_1^2 + 7x_2^2 - 3x_3^2 + 4x_1 x_2 - 2x_1 x_3 + 8x_2 x_3$$

$$\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 7 & 4 \\ -1 & 4 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Theorem: If A is a symmetric matrix, Then

(a) $x^T A x$ is positive definite Eigen value of $A > 0$

(b) $x^T A x$ is negative definite Eigen value of $A < 0$

(c) $x^T A x$ is Indefinite iff at least one positive & one negative.

Q: Find the nature of the Quadratic form

$$(a) x^2 + 5y^2 + z^2 + 2xy + 2yz + 6zx$$

$$(b) 3x^2 + 5y^2 + 3z^2 - 2yz + 2zx - 2xy.$$

$$(a) x^2 + 5y^2 + z^2 + 2xy + 2yz + 6zx$$

$\begin{bmatrix} 1 & 1 & 3 \\ 1 & 5 & 1 \\ 3 & 1 & 1 \end{bmatrix}$, The Eigen values of A
is -2, 3, 6

so give quadratic form is Indefinit from
part c of theorem

$$(b) 3x^2 + 5y^2 + 3z^2 - 2yz + 2zx - 2xy$$

$$\begin{bmatrix} 3 & -1 & 1 \\ -1 & 5 & -1 \\ 1 & -1 & 3 \end{bmatrix}$$

The Eigen values of A are 2, 3, 6

so the given quadratic form is positive definit

Conjugate Transpose:

If A is complex, Then $A^* = \bar{A}^T$

Q: Find a conjugate transpose of $A = \begin{bmatrix} i+i & -i & 0 \\ 2 & 3-2i & i \end{bmatrix}$

$$\bar{A} = \begin{bmatrix} 1-i & i & 0 \\ 2 & 3+2i & -i \end{bmatrix}$$

$$\bar{A}^T = \begin{bmatrix} 1-i & 2 \\ 1 & 3+2i \\ 0 & -i \end{bmatrix} = A^*$$

Defn: (a) unitary if $A^{-1} = A^*$

Hermitian if $A^* = A$

(b) E.V of H.M is real

Q. Find the E.V of Hermitian matrix

$$A = \begin{bmatrix} 2 & 1+i \\ 1-i & 3 \end{bmatrix}$$

S. The characteristic equation is

$$|\lambda I - A| = \begin{vmatrix} \lambda - 2 & -1-i \\ -1+i & \lambda - 3 \end{vmatrix}$$

$$= (\lambda - 2)(\lambda - 3) - (-1-i)(-1+i)$$

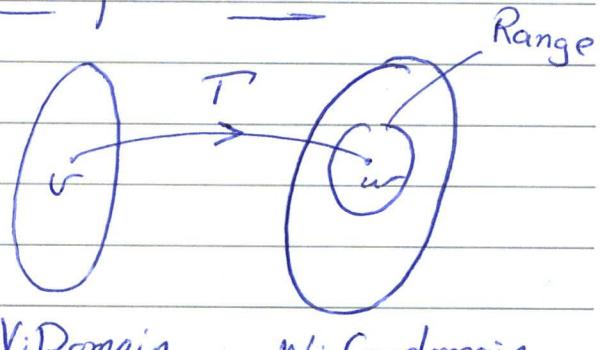
$$= (\lambda^2 - 5\lambda + 6) - 2$$

$$= (\lambda - 1)(\lambda - 4)$$

$$\lambda = 1, 4 \text{ which are real.}$$

Week 11

Chapter 8: Linear Transformation.



Function T that maps a vector space V into a vector space W .

Q: $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ $v = (v_1, v_2) \in \mathbb{R}^2$, $T(v_1, v_2) = (v_1 - v_2, v_1 + 2v_2)$

- (a) Find the image of $v(-1, 2)$ (b) Find the Pre-image of $w(-1, 11)$

Soln.

(a) $v = (-1, 2)$

$$T(v) = T(-1, 2) = (-1 - 2, -1 + 2(2)) = (-3, 3)$$

(b) $T(v) = w = (-1, 11)$

we know $T(v_1, v_2) = (v_1 - v_2, v_1 + 2v_2) = (-1, 11)$

so compare the elements

$$\begin{aligned} v_1 - v_2 &= -1 \\ -v_1 + 2v_2 &= 11 \\ \hline -3v_2 &= -12 \end{aligned}$$

$$v_2 = 4$$

$$v_1 - 4 = -1$$

$$v_1 = -1 + 4 = -1 + 4 = 3$$

$$v_1 = 3 \quad v_2 = 4$$

$(3, 4)$ is the image of $(-1, 11)$

Linear Transformation: Let v, w be the V.S
 $\bar{T}: V \rightarrow W$: v to w Linear Transformation (L.T.).
 if (a) $\bar{T}(u+v) = T(u) + T(v)$ $\forall u, v \in V$
 (b) $\bar{T}(cu) = cT(u)$ $\forall c \in \mathbb{R}$

Q: Verify a L.T. from \mathbb{R}^2 into \mathbb{R}^2

$$\bar{T}(v_1, v_2) = (v_1 - v_2, v_1 + 2v_2) \rightarrow ①$$

Soln: Let $u = (u_1, u_2)$ and $v = (v_1, v_2)$ & c is any real number.

$$(a) \text{ Let } u+v = (u_1 + u_2) + (v_1 + v_2) = (u_1 + v_1, u_2 + v_2)$$

$$\begin{aligned} \text{so } \bar{T}(u+v) &= \bar{T}(u_1 + v_1, u_2 + 2v_2) \\ &= ((u_1 + v_1) - (u_2 + v_2), (u_1 + v_1) + 2(u_2 + v_2)) \\ &= ((u_1 - u_2) + (v_1 - v_2), (u_1 + 2u_2) + (v_1 + 2v_2)) \\ &= ((u_1 - u_2), (u_1 + 2u_2)) + ((v_1 - v_2), (v_1 + 2v_2)) \\ &= \bar{T}(u) + \bar{T}(v) \quad \text{from ①} \end{aligned}$$

$$(b) \text{ Let } cu = c(u_1, u_2) = (cu_1, cu_2)$$

$$\begin{aligned} \bar{T}(cu) &= \bar{T}(cu_1, cu_2) \\ &= ((cu_1 - cu_2), (cu_1 + 2cu_2)) \\ &= (c(u_1 - u_2), c(u_1 + 2u_2)) \\ &= c((u_1 - u_2), (u_1 + 2u_2)) \\ &= c\bar{T}(u) \end{aligned}$$

Therefore \bar{T} is a Linear Transformation

Zero Transformation: $T: V \rightarrow W$, $T(v) = 0 \quad \forall v \in V$

Identity Transformation: $T: V \rightarrow W$, $T(v) = v \quad \forall v \in V$

Q: Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a L.T such that

$$T(1, 0, 0) = (2, -1, 4)$$

$$T(0, 1, 0) = (1, 5, -2)$$

$$T(0, 0, 1) = (0, 3, 1)$$

Find $T(2, 3, -2)$

Soln: we can write

$$(2, 3, -2) = 2(1, 0, 0) + 3(0, 1, 0) - 2(0, 0, 1)$$

$$T(2, 3, -2) = 2T(1, 0, 0) + 3T(0, 1, 0) - 2T(0, 0, 1)$$

$$= 2(2, -1, 4) + 3(1, 5, -2) - 2(0, 3, 1)$$

$$= (4, -2, 8) + (3, 15, -6) - (0, 6, 2)$$

$$= (7, 7, 0)$$

Q: The function $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is defined by

$$T(v) = Av = \begin{bmatrix} 3 & 0 \\ 2 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

Find $T(v)$ where $v(2, -1)$

Soln. $v = (2, -1)$

$$T(v) = Av = \begin{bmatrix} 3 & 0 \\ 2 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \\ 0 \end{bmatrix}$$

$$T(2, -1) = (6, 3, 0)$$

Kernal of L.T:

Let $T: V \rightarrow W$ be a L.T Then the set of all vectors v in V that satisfy $T(v) = 0$ is called the kernal of T . and it is denoted by $\ker(T)$

$$\ker(T) = \{ v \in V \mid T(v) = 0 \}$$

or Null space of T .

Range of L.T:

Let $T: V \rightarrow W$ be a L.T.

Then the set of all vectors w in W that are images of vectors in V is called range of T and it is denoted by Range

Rank of L.T.

$\text{rank}(T)$ = The dimension of The range of T

Nullity of L.T:

$\text{nullity}(T)$: The dimension of kernal of T

Dimension Theorem for a L.T.

Let $T: V \rightarrow W$ be a L.T

$$\text{rank}(T) + \text{nullity}(T) = n$$

OR

$$\dim(\text{range of } T) + \dim(\ker T) = \dim(\text{domain of } T)$$

Q: Find the rank and nullity of a L.T

$$A = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Soln. Rank = 2 No. of Non-zero Rows.
and $n = 3$

so by Rank nullity Theorem

$$\text{rank}(T) + \text{nullity}(T) = n$$
$$\text{nullity } T = 3 - 2 = 1$$

one-one:

onto:

Q: Find the standard matrix for the L-T
 $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by
 $T(x, y, z) = (x - 2y, 2x + y) \rightarrow ①$

$$T(e_1) = T(1, 0, 0) = (1 - 2 \cdot 0, 2 \cdot 1 + 0) \\ = (1, 2) \text{ from } ①$$

In Matrix Notation

$$T(e_1) = T \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$T(e_2) = T(0, 1, 0) = (0 - 2 \cdot 1, 2 \cdot 0 + 1) = (-2, 1)$$

$$T(e_2) = T \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

$$T(e_3) = T(0, 0, 1) = (0, 0)$$

$$T(e_3) = T \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$A = [T(e_1), T(e_2), T(e_3)] = \begin{bmatrix} 1 & -2 & 0 \\ 2 & 1 & 0 \end{bmatrix}$$

Week 12: Chapter 9 Numerical Methods

LU-Decomposition:

Step1: Reduce the matrix to Row Echelon form.

Step2: In each position along the main diagonal of L, place Reciprocal of the multiplier.

Step3: In each position along the main diagonal of L, place ~~← phasor~~ the negative of the multiplier.

Step4: From the decomposition $A = LU$

Q: Find a LU-decomposition $A = \begin{bmatrix} 6 & -2 & 0 \\ 9 & -1 & 1 \\ 3 & 7 & 5 \end{bmatrix}$

Soln: Given

$$A = \begin{bmatrix} 6 & -2 & 0 \\ 9 & -1 & 1 \\ 3 & 7 & 5 \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ x & 1 & 0 \\ x^2 & x & 1 \\ x^3 & x^2 & x \end{bmatrix}$$

multiplier $\frac{1}{6}$ = $\begin{bmatrix} 1 & -\frac{1}{3} & 0 \\ 9 & -1 & 1 \\ 3 & 7 & 5 \end{bmatrix}$

multiplier -9 = $\begin{bmatrix} 1 & -\frac{1}{3} & 0 \\ 0 & 2 & 1 \\ 0 & 8 & 5 \end{bmatrix}$

multiplier $\frac{1}{2}$ = $\begin{bmatrix} 1 & -\frac{1}{3} & 0 \\ 0 & 1 & \frac{1}{2} \\ 0 & 8 & 5 \end{bmatrix}$

multiplier -8 = $\begin{bmatrix} 1 & -\frac{1}{3} & 0 \\ 0 & 1 & \frac{1}{2} \\ 0 & 0 & 1 \end{bmatrix}$

multiplier -1 = $\begin{bmatrix} 1 & -\frac{1}{3} & 0 \\ 0 & 1 & \frac{1}{2} \\ 0 & 0 & 1 \end{bmatrix}$

$$A = L U = \begin{bmatrix} 6 & 0 & 0 \\ 9 & 2 & 0 \\ 3 & 8 & 1 \end{bmatrix} \begin{bmatrix} 1 & -\frac{1}{3} & 0 \\ 0 & 1 & \frac{1}{2} \\ 0 & 0 & 1 \end{bmatrix}$$

The Power Method:

Step1: choose an arbitrary non-zero vector.

Step2: Compute Ax_0 and multiply it by $\frac{1}{\max(Ax_0)}$

Step3: Compute Ax_1 and multiply it by $\frac{1}{\max(Ax_1)}$

Q: Apply the power method with maximum entry scaling to $A = \begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix}$ with $x_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ upto x_5 .

Soln. $Ax_0 = \begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$

and $x_1 = \frac{Ax_0}{\max(Ax_0)} = \frac{1}{3} \begin{bmatrix} 3 \\ 2 \end{bmatrix} \approx \begin{bmatrix} 1.000 \\ 0.6667 \end{bmatrix}$

Now

$$Ax_1 = \begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 0.667 \end{bmatrix} \approx \begin{bmatrix} 4.3333 \\ 4.0000 \end{bmatrix}$$

$$x_2 = \frac{Ax_1}{\max(Ax_1)} = \frac{1}{4.333} \begin{bmatrix} 4.333 \\ 4.000 \end{bmatrix} \approx \begin{bmatrix} 1.00000 \\ 0.92308 \end{bmatrix}$$

$$Ax_2 = \begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1.00000 \\ 0.92308 \end{bmatrix} \approx \begin{bmatrix} 4.84615 \\ 4.76923 \end{bmatrix}$$

$$x_3 = \frac{Ax_2}{\max(Ax_2)} = \frac{1}{4.84615} \begin{bmatrix} 4.84615 \\ 4.76923 \end{bmatrix} \approx \begin{bmatrix} 1.0000 \\ 0.98413 \end{bmatrix}$$

$$AX_3 = \begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1.00000 \\ 0.98413 \end{bmatrix} \approx \begin{bmatrix} 4.96825 \\ 4.95238 \end{bmatrix}$$

$$X_4 = \frac{AX_3}{\max(AX_3)} = \frac{1}{4.96825} \begin{bmatrix} 4.96825 \\ 4.95238 \end{bmatrix} \approx \begin{bmatrix} 1.00000 \\ 0.9968 \end{bmatrix}$$

$$AX_4 = \begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1.00000 \\ 0.9968 \end{bmatrix} = \begin{bmatrix} \quad \\ \quad \end{bmatrix}$$

$$X_5 = \frac{AX_4}{\max(AX_4)} =$$

Singular Value Decomposition:

If A is $m \times n$ matrix and if $\lambda_1, \lambda_2, \dots$ are the eigen value of $A^T A$.

Then the number $\sigma_1 = \sqrt{\lambda_1}, \sigma_2 = \sqrt{\lambda_2}, \dots$ are called the singular value of A.

Q: Find the singular value decomposition of the matrix $\begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}$.

Soln. First we find $A^T A$ is

$$A^T A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

Now find the Eigen value

The characteristic of $\tilde{A}^T \tilde{A}$ is

$$(\lambda I - \tilde{A}^T \tilde{A}) = \begin{vmatrix} \lambda - 2 & -1 \\ -1 & \lambda - 2 \end{vmatrix} = 0$$

$$\lambda = 3, 1$$

$$\text{so } \lambda_1 = 3 \quad \& \quad \lambda_2 = 1$$

$$\sigma_1 = \sqrt{\lambda_1} = \sqrt{3}, \quad \sigma_2 = \sqrt{\lambda_2} = \sqrt{1} = 1$$

The Eigen vector corresponding to these E.V

$$v_1 = \begin{bmatrix} \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix}, \quad v_2 = \begin{bmatrix} \frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} \end{bmatrix}$$

Now, to find u_i where $u_i = \frac{1}{\sigma_i} A v_i$

$$\text{so } u_1 = \frac{1}{\sigma_1} A v_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix}$$

$$= \begin{bmatrix} \sqrt{6}/3 \\ \sqrt{6}/6 \\ \sqrt{6}/6 \end{bmatrix}$$

$$u_2 = \frac{1}{\sigma_2} A v_2 = \frac{1}{1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \sqrt{2}/2 \\ -\sqrt{2}/2 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ -\sqrt{2}/2 \\ \sqrt{2}/2 \end{bmatrix}$$

$$u_3 = \begin{bmatrix} -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}$$

Now, The singular value of decomposition of A
is

$$A = U \Sigma V^T$$

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{6}}{3} & 0 & -\frac{1}{\sqrt{3}} \\ \frac{\sqrt{6}}{6} & \frac{-\sqrt{2}}{2} & \frac{1}{\sqrt{3}} \\ \frac{\sqrt{6}}{6} & \frac{\sqrt{2}}{2} & \frac{1}{\sqrt{3}} \end{bmatrix} \begin{bmatrix} \sqrt{3} & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \end{bmatrix}$$